

Scania Fault Codes Abs

This text aims to present and discuss the innovative Volvo Uddevalla plant, comparing it to other plants - Japanese lean ones and others. The starting point for the book is Volvo's dramatic decision to close its Uddevalla and Kalmar plants, and the debate that followed this decision, both in Sweden and abroad. Both plants were pioneers of the possibilities to unite productivity and the good work, but, following the announcement of their closure, researchers and practitioners in the field of industrial organization from many countries asked why they closed, how they compared with other production concepts, and whether we now see an end of an alternative to Japanese lean production.

This book constitutes the proceedings of the 38th International Conference on Computer Safety, Reliability and Security, SAFECOMP 2019, held in Turku, Finland, in September 2019. The 16 full and 5 short papers included in this volume were carefully reviewed and selected from 65 submissions. They were organized in topical sections named: formal verification; autonomous driving; safety and reliability modeling; security engineering and risk assessment; safety argumentation; verification and validation of autonomous systems; and interactive systems and design validation.

Simulation of Power Electronics Converters Using PLECS® is a guide to simulating a power electronics circuit using the latest powerful software for power electronics circuit simulation purposes. This book assists engineers gain an increased understanding of circuit operation so they can, for a given set of specifications, choose a topology, select appropriate circuit component types and values, estimate circuit performance, and complete the design by ensuring that the circuit performance will meet specifications even with the anticipated variations in operating conditions and circuit component values. This book covers the fundamentals of power electronics converter simulation, along with an analysis of power electronics converters using PLECS. It concludes with real-world simulation examples for applied content, making this book useful for all those in the electrical and electronic engineering field. Contains unique examples on the simulation of power electronics converters using PLECS® Includes explanations and guidance on all included simulations for re-doing the simulations Incorporates analysis and design for rapidly creating power electronics circuits with high accuracy

Pounder's Marine Diesel Engines and Gas Turbines, Tenth Edition, gives engineering cadets, marine engineers, ship operators and managers insights into currently available engines and auxiliary equipment and trends for the future. This new edition introduces new engine models that will be most commonly installed in ships over the next decade, as well as the latest legislation and pollutant emissions procedures. Since publication of the last edition in 2009, a number of emission control areas (ECAs) have been established by the International Maritime Organization (IMO) in which exhaust emissions are subject to even more stringent controls. In addition, there are now rules that affect new ships and their emission of CO2 measured as a product of cargo carried. Provides the latest emission control technologies, such as SCR and water scrubbers Contains complete updates of legislation and pollutant emission procedures Includes the latest emission control technologies and expands upon remote monitoring and control of engines

"Parallel corpora, parallel worlds""Selected papers from a symposium on parallel and comparable corpora at Uppsala University, Sweden, 22-23 April, 1999"BRILLBehavior Trees in Robotics and AIAn IntroductionCRC Press

In a dramatic unveiling of the little-known world of contracted military logistics, Adam Moore examines the lives of the global army of laborers who support US overseas wars. Empire's Labor brings us the experience of the hundreds of thousands of men and women who perform jobs such as truck drivers and administrative assistants at bases located in warzones in the Middle East and Africa. He highlights the changes the US military has undergone since the Vietnam War, when the ratio of contractors to uniformed personnel was roughly 1:6. In Afghanistan it has been as high as 4:1. This growth in logistics contracting represents a fundamental change in how the US fights wars, with the military now dependent on a huge pool of contractors recruited from around the world. It also, Moore demonstrates, has social, economic, and political implications that extend well beyond the battlefields. Focusing on workers from the Philippines and Bosnia, two major sources of "third country national" (TCN) military labor, Moore explains the rise of large-scale logistics outsourcing since the end of the Cold War; describes the networks, infrastructures, and practices that span the spaces through which people, information, and goods circulate; and reveals the experiences of foreign workers, from the hidden dynamics of labor activism on bases, to the economic and social impacts these jobs have on their families and the communities they hail from. Through his extensive fieldwork and interviews, Moore gives voice to the agency and aspirations of the many thousands of foreigners who labor for the US military. Thanks to generous funding from UCLA and its participation in TOME (Toward an Open Monograph Ecosystem), the ebook editions of this book are available as Open Access volumes from Cornell Open (cornellopen.org) and other repositories.

This comprehensive text/reference presents an in-depth review of the state of the art of automotive connectivity and cybersecurity with regard to trends, technologies, innovations, and applications. The text describes the challenges of the global automotive market, clearly showing where the multitude of innovative activities fit within the overall effort of cutting-edge automotive innovations, and provides an ideal framework for understanding the complexity of automotive connectivity and cybersecurity.

Topics and features: discusses the automotive market, automotive research and development, and automotive electrical/electronic and software technology; examines connected cars and autonomous vehicles, and methodological approaches to cybersecurity to avoid cyber-attacks against vehicles; provides an overview on the automotive industry that introduces the trends driving the automotive industry towards smart mobility and autonomous driving; reviews automotive research and development, offering background on the complexity involved in developing new vehicle models; describes the technologies essential for the evolution of connected cars, such as cyber-physical systems and the Internet of Things; presents case studies on Car2Go and car sharing, car hailing and ridesharing, connected parking, and advanced driver assistance systems; includes review questions and exercises at the end of each chapter. The insights offered by this practical guide will be of great value to graduate students, academic researchers and professionals in industry seeking to learn about the advanced methodologies in automotive connectivity and cybersecurity.

This book combines comprehensive multi-angle discussions on fully connected and automated vehicle highway implementation. It covers the current progress of the works towards autonomous vehicle highway development, which encompasses the discussion on the technical, social, and policy as well as security aspects of Connected and Autonomous Vehicles (CAV) topics. This, in return, will be beneficial to a vast amount of readers who are interested in

the topics of CAV, Automated Highway and Smart City, among many others. Topics include, but are not limited to, Autonomous Vehicle in the Smart City, Automated Highway, Smart-Cities Transportation, Mobility as a Service, Intelligent Transportation Systems, Data Management of Connected and Autonomous Vehicle, Autonomous Trucks, and Autonomous Freight Transportation. Brings together contributions discussing the latest research in full automated highway implementation; Discusses topics such as autonomous vehicles, intelligent transportation systems, and smart highways; Features contributions from researchers, academics, and professionals from a broad perspective.

A strategy for changing attitudes about personal finances covers such topics as getting out of debt, the dangers of cash advances and keeping spending within income limits.

Behavior Trees (BTs) provide a way to structure the behavior of an artificial agent such as a robot or a non-player character in a computer game. Traditional design methods, such as finite state machines, are known to produce brittle behaviors when complexity increases, making it very hard to add features without breaking existing functionality. BTs were created to address this very problem, and enables the creation of systems that are both modular and reactive. Behavior Trees in Robotics and AI: An Introduction provides a broad introduction as well as an in-depth exploration of the topic, and is the first comprehensive book on the use of BTs. This book introduces the subject of BTs from simple topics, such as semantics and design principles, to complex topics, such as learning and task planning. For each topic, the authors provide a set of examples, ranging from simple illustrations to realistic complex behaviors, to enable the reader to successfully combine theory with practice. Starting with an introduction to BTs, the book then describes how BTs relate to, and in many cases, generalize earlier switching structures, or control architectures. These ideas are then used as a foundation for a set of efficient and easy to use design principles. The book then presents a set of important extensions and provides a set of tools for formally analyzing these extensions using a state space formulation of BTs. With the new analysis tools, the book then formalizes the descriptions of how BTs generalize earlier approaches and shows how BTs can be automatically generated using planning and learning. The final part of the book provides an extended set of tools to capture the behavior of Stochastic BTs, where the outcomes of actions are described by probabilities. These tools enable the computation of both success probabilities and time to completion. This book targets a broad audience, including both students and professionals interested in modeling complex behaviors for robots, game characters, or other AI agents. Readers can choose at which depth and pace they want to learn the subject, depending on their needs and background.

This publication examines the opportunities and challenges, for business and government, associated with technologies bringing about the "next production revolution". These include a variety of digital technologies (e.g. the Internet of Things and advanced robotics), industrial biotechnology, 3D printing, new materials and nanotechnology. Some of these technologies are already used in production, while others will be available in the near future. All are developing rapidly. As these technologies transform the production and the distribution of goods and services, they will have far-reaching consequences for productivity, skills, income distribution, well-being and the environment. The more that governments and firms understand how production could develop in the near future, the better placed they will be to address the risks and reap the benefits.

Through a series of studies, the overarching aim of this book is to investigate if and how the digitalization/digital transformation process affects various welfare services provided by the public sector, and the ensuing implications thereof. Ultimately, this book seeks to understand if it is conceivable for digital advancement to result in the creation of private/non-governmental alternatives to welfare services, possibly in a manner that transcends national boundaries. This study also investigates the possible ramifications of technological development for the public sector and the Western welfare society at large. This book takes its point of departure from the 2016 Organization for Economic Co-operation and Development (OECD) report that targets specific public service areas in which government needs to adopt new strategies not to fall behind. Specifically, this report emphasizes the focus on digitalization of health care/social care, education, and protection services, including the use of assistive technologies referred to as "digital welfare." Hence, this book explores the factors potentially leading to whether state actors could be overrun by other non-governmental actors, disrupting the current status quo of welfare services. The book seeks to provide an innovative, enriching, and controversial take on society at large and how various aspects of the public sector can be, and are, affected by the ongoing digitalization process in a way that is not covered by extant literature on the market. This book takes its point of departure in Sweden given the fact that Sweden is one of the most digitalized countries in Europe, according to the Digital Economy and Society Index (DESI), making it a pertinent research case. However, as digitalization transcends national borders, large parts of the subject matter take on an international angle. This includes cases from several other countries around Europe as well as the United States.

Here is the latest edition of a compact reference that has been a real treasure for materials personnel for more than 15 years. Packed with pictures, definitions, and descriptions of ANSI and API piping materials, such as flanges, fittings, bolts, gaskets, and required wrench sizes, it serves as an excellent guide for "rookies" and a ready reference for "old-timers" alike. This compact reference is packed with pictures, definitions, and descriptions of ANSI and API piping materials, such as flanges, fittings, bolts, gaskets, and required wrench sizes. It contains basic information and data to answer common questions that arise in materials handling, pipe fitting, and engineering.

The present catalog provides a compilation of all supra- and (infra-) specific taxa of extant and fossil Valvatidae (Ectobranchia), a group of freshwater operculate snails (Gastropoda, Heterobranchia). Taxa initially described in this family and subsequently classified in other families (in particular Hydrobiidae and Planorbidae, but among others also larval shells of trichopteran insects) as well as names due to errors or misspellings are likewise included. For each taxon the full original reference and the type locality (and type horizon in fossils) is provided. Remarks on nomenclatorial problems

and possible solutions are added if necessary. As a novelty the extensive reference list is as far as possible directly linked to the internet source (digital view or pdf-download) of the respective papers to facilitate future taxonomic research.

As deepwater wells are drilled to greater depths, pipeline engineers and designers are confronted with new problems such as water depth, weather conditions, ocean currents, equipment reliability, and well accessibility. Subsea Pipeline Design, Analysis and Installation is based on the authors' 30 years of experience in offshore. The authors provide rigorous coverage of the entire spectrum of subjects in the discipline, from pipe installation and routing selection and planning to design, construction, and installation of pipelines in some of the harshest underwater environments around the world. All-inclusive, this must-have handbook covers the latest breakthroughs in subjects such as corrosion prevention, pipeline inspection, and welding, while offering an easy-to-understand guide to new design codes currently followed in the United States, United Kingdom, Norway, and other countries. Gain expert coverage of international design codes Understand how to design pipelines and risers for today's deepwater oil and gas Master critical equipment such as subsea control systems and pressure piping

There are many distinct pleasures associated with computer programming. Craftsmanship has its quiet rewards, the satisfaction that comes from building a useful object and making it work. Excitement arrives with the flash of insight that cracks a previously intractable problem. The spiritual quest for elegance can turn the hacker into an artist. There are pleasures in parsimony, in squeezing the last drop of performance out of clever algorithms and tight coding. The games, puzzles, and challenges of problems from international programming competitions are a great way to experience these pleasures while improving your algorithmic and coding skills. This book contains over 100 problems that have appeared in previous programming contests, along with discussions of the theory and ideas necessary to attack them. Instant online grading for all of these problems is available from two WWW robot judging sites. Combining this book with a judge gives an exciting new way to challenge and improve your programming skills. This book can be used for self-study, for teaching innovative courses in algorithms and programming, and in training for international competition. The problems in this book have been selected from over 1,000 programming problems at the Universidad de Valladolid online judge. The judge has ruled on well over one million submissions from 27,000 registered users around the world to date. We have taken only the best of the best, the most fun, exciting, and interesting problems available.

Accessible to all readers, including students of secondary school and amateur technology enthusiasts, Robotics, Mechatronics, and Artificial Intelligence simplifies the process of finding basic circuits to perform simple tasks, such as how to control a DC or step motor, and provides instruction on creating moving robotic parts, such as an "eye" or an "ear." Though many companies offer kits for project construction, most experimenters want to design and build their own robots and other creatures specific to their needs and goals. With this new book by Newton Braga, hobbyists and experimenters around the world will be able to decide what skills they want to feature in a project and then choose the right "building blocks" to create the ideal results. In the past few years the technology of robotics, mechatronics, and artificial intelligence has exploded, leaving many people with the desire but not the means to build their own projects. The author's fascination with and expertise in the exciting field of robotics is demonstrated by the range of simple to complex project blocks he provides, which are designed to benefit both novice and experienced robotics enthusiasts. The common components and technology featured in the project blocks are especially beneficial to readers who need practical solutions that can be implemented easily by their own hands, without incorporating expensive, complicated technology. Accessible to technicians and hobbyists with many levels of experience, and written to provide inexpensive and creative fun with robotics Appeals to all sorts of technology enthusiasts, including those involved with electronics, computers, home automation, mechanics, and other areas

A Clear Outline of Current Methods for Designing and Implementing Automotive Systems Highlighting requirements, technologies, and business models, the Automotive Embedded Systems Handbook provides a comprehensive overview of existing and future automotive electronic systems. It presents state-of-the-art methodological and technical solutions in the areas of in-vehicle architectures, multipartner development processes, software engineering methods, embedded communications, and safety and dependability assessment. Divided into four parts, the book begins with an introduction to the design constraints of automotive-embedded systems. It also examines AUTOSAR as the emerging de facto standard and looks at how key technologies, such as sensors and wireless networks, will facilitate the conception of partially and fully autonomous vehicles. The next section focuses on networks and protocols, including CAN, LIN, FlexRay, and TTCAN. The third part explores the design processes of electronic embedded systems, along with new design methodologies, such as the virtual platform. The final section presents validation and verification techniques relating to safety issues. Providing domain-specific solutions to various technical challenges, this handbook serves as a reliable, complete, and well-documented source of information on automotive embedded systems.

Cartography and geographic information (GI) are remarkably appropriate for the requirements of early warning (EW) and crisis management (CM). The use of geospatial technology has increased tremendously in the last years. ICT has changed from just using maps created in advance, to new approaches, allowing individuals (decision-makers) to use cartography interactively, on the basis of individual user's requirements. The new generation of cartographic visualizations based on standardisation, formal modelling, use of sensors, semantics and ontology, allows for the better adaptation of information to the needs of the users. In order to design a new framework in pre-disaster and disaster management safety/security/privacy aspects of institutions and citizens need to be considered. All this can only be achieved by demonstrating new research achievements, sharing best practices (e.g. in the health area) and working towards the wider acceptance of geospatial technology in society, with the help of education and media. This book will outline research frontiers and applications of cartography and GI in EW and CM and document their roles and potentials

in wider processes going on in information/knowledge-based societies.

Author Vizard covers blending the bowls, basic porting procedures, as well as pocket porting, porting the intake runners, and many advanced procedures. Advanced procedures include unshrouding valves and developing the ideal port area and angle.

A key aspect of cyber-physical systems (CPS) is their potential for integrating information technologies with embedded control systems and physical systems to form new or improved functionalities. CPS thus draws upon advances in many areas. This positioning provides unprecedented opportunities for innovation, both within and across existing domains. However, at the same time, it is commonly understood that we are already stretching the limits of existing methodologies. In embarking towards CPS with such unprecedented capabilities, it becomes essential to improve our understanding of CPS complexity and how we can deal with it. Complexity has many facets, including complexity of the CPS itself, of the environments in which the CPS acts, and in terms of the organizations and supporting tools that develop, operate, and maintain CPS. This book is a result of a journal Special Issue, with the objective of providing a forum for researchers and practitioners to exchange their latest achievements and to identify critical issues, challenges, opportunities, and future directions for how to deal with the complexity of future CPS. The contributions include 10 papers on the following topics: (I) Systems and Societal Aspects Related to CPS and Their Complexity; (II) Model-Based Development Methods for CPS; (III) CPS Resource Management and Evolving Computing Platforms; and (IV) Architectures for CPS.

Featuring contributions from major technology vendors, industry consortia, and government and private research establishments, the Industrial Communication Technology Handbook, Second Edition provides comprehensive and authoritative coverage of wire- and wireless-based specialized communication networks used in plant and factory automation, automotive applications, avionics, building automation, energy and power systems, train applications, and more. New to the Second Edition: 46 brand-new chapters and 21 substantially revised chapters Inclusion of the latest, most significant developments in specialized communication technologies and systems Addition of new application domains for specialized networks The Industrial Communication Technology Handbook, Second Edition supplies readers with a thorough understanding of the application-specific requirements for communication services and their supporting technologies. It is useful to a broad spectrum of professionals involved in the conception, design, development, standardization, and use of specialized communication networks as well as academic institutions engaged in engineering education and vocational training.

This book presents operational and practical issues of automotive mechatronics with special emphasis on the heterogeneous automotive vehicle systems approach, and is intended as a graduate text as well as a reference for scientists and engineers involved in the design of automotive mechatronic control systems. As the complexity of automotive vehicles increases, so does the dearth of high competence, multi-disciplined automotive scientists and engineers. This book provides a discussion into the type of mechatronic control systems found in modern vehicles and the skills required by automotive scientists and engineers working in this environment. Divided into two volumes and five parts, Automotive Mechatronics aims at improving automotive mechatronics education and emphasises the training of students' experimental hands-on abilities, stimulating and promoting experience among high education institutes and produce more automotive mechatronics and automation engineers. The main subject that are treated are: VOLUME I: RBW or XBW unibody or chassis-motion mechatronic control hypersystems; DBW AWD propulsion mechatronic control systems; BBW AWB dispulsion mechatronic control systems; VOLUME II: SBW AWS diversion mechatronic control systems; ABW AWA suspension mechatronic control systems. This volume was developed for undergraduate and postgraduate students as well as for professionals involved in all disciplines related to the design or research and development of automotive vehicle dynamics, powertrains, brakes, steering, and shock absorbers (dampers). Basic knowledge of college mathematics, college physics, and knowledge of the functionality of automotive vehicle basic propulsion, dispulsion, conversion and suspension systems is required.

Continuing the tradition of International Dyke Conference, this book is largely based on contributions from the IDC7 but also includes some chapters by invitation. It focuses on mafic dyke swarms and related associations: e.g. links with sills, kimberlites, syenites, carbonatites, and volcanics, discussing the following themes: (i) regional maps/reviews of dyke swarms and related units, (ii) the role of giant dyke swarms in the reconstruction of supercontinents/paleocontinents, (iii) mapping of dykes using remote sensing techniques, (iv) geochronology of dyke swarms, (v) petrology, geochemistry and petrogenesis of dykes, (vi) emplacement mechanism of dykes, (vii) dyke swarms and planetary bodies, and (viii) links to mineralization and resources.

This congress proceedings provides recent research on leading-edge manufacturing processes. The aim of this scientific congress is to work out diverse individual solutions of "production in the border area" and transferable methodological approaches. In addition, guest speakers with different backgrounds will give the congress participants food for thoughts, interpretations, views and suggestions. The manufacturing industry is currently undergoing a profound structural change, which on the one hand produces innovative solutions through the use of high-performance communication and information technology, and on the other hand is driven by new requirements for goods, especially in the mobility and energy sector. With the social discourse on how we should live and act primarily according to guidelines of sustainability, structural change is gaining increasing dynamic. It is essential to translate politically specified sustainability goals into socially accepted and marketable technical solutions. Production research is meeting this challenge and will make important contributions and provide innovative solutions from different perspectives.

This is the fifth volume of a sub series on Road Vehicle Automation published within the Lecture Notes in Mobility. Like in previous editions, scholars, engineers and analysts from all around the world have contributed chapters covering human factors, ethical, legal, energy and technology aspects related to automated vehicles, as well as transportation infrastructure and public planning. The book is based on the Automated Vehicles Symposium which was hosted by the Transportation Research Board (TRB) and the Association for Unmanned Vehicle Systems International (AUVSI) in San Francisco, California (USA) in July 2017.

This book focuses on natural gas and synthetic methane as contemporary and future energy sources. Following a historical overview, physical and chemical properties, occurrence, extraction, transportation and storage of natural gas are discussed. Sustainable production of natural gas and methane as well as production and storage of synthetic methane are scrutinized next. A substantial part of the book addresses construction of vehicles for natural and synthetic methane as well as large engines for industrial and maritime use. The last chapters present some perspectives on further uses of renewable liquid fuels as well as

natural gas for industrial engines and gas power plants.

The race is on to construct the first quantum code breaker, as the winner will hold the key to the entire Internet. From international, multibillion-dollar financial transactions to top-secret government communications, all would be vulnerable to the secret-code-breaking ability of the quantum computer. Written by a renowned quantum physicist closely involved in the U.S. government's development of quantum information science, Schrödinger's Killer App: Race to Build the World's First Quantum Computer presents an inside look at the government's quest to build a quantum computer capable of solving complex mathematical problems and hacking the public-key encryption codes used to secure the Internet. The "killer application" refers to Shor's quantum factoring algorithm, which would unveil the encrypted communications of the entire Internet if a quantum computer could be built to run the algorithm. Schrödinger's notion of quantum entanglement—and his infamous cat—is at the heart of it all. The book develops the concept of entanglement in the historical context of Einstein's 30-year battle with the physics community over the true meaning of quantum theory. It discusses the remedy to the threat posed by the quantum code breaker: quantum cryptography, which is unbreakable even by the quantum computer. The author also covers applications to other important areas, such as quantum physics simulators, synchronized clocks, quantum search engines, quantum sensors, and imaging devices. In addition, he takes readers on a philosophical journey that considers the future ramifications of quantum technologies. Interspersed with amusing and personal anecdotes, this book presents quantum computing and the closely connected foundations of quantum mechanics in an engaging manner accessible to non-specialists. Requiring no formal training in physics or advanced mathematics, it explains difficult topics, including quantum entanglement, Schrödinger's cat, Bell's inequality, and quantum computational complexity, using simple analogies.

This book addresses the issue of the best way to build effective knowledge-based systems for handling different types of diagnostic problems. It presents examples of different solutions to building effective diagnostic systems, and helps the reader to decide on an appropriate strategy for building a system. The book makes the material easy to understand and goes through the different options for constructing diagnostic systems.

Written by two of the most respected, experienced and well-known researchers and developers in the field (e.g., Kiencke worked at Bosch where he helped develop anti-breaking system and engine control; Nielsen has lead joint research projects with Scania AB, Mecel AB, Saab Automobile AB, Volvo AB, Fiat GM Powertrain AB, and DaimlerChrysler. Reflecting the trend to optimization through integrative approaches for engine, driveline and vehicle control, this valuable book enables control engineers to understand engine and vehicle models necessary for controller design and also introduces mechanical engineers to vehicle-specific signal processing and automatic control. Emphasis on measurement, comparisons between performance and modelling, and realistic examples derive from the authors' unique industrial experience. The second edition offers new or expanded topics such as diesel-engine modelling, diagnosis and anti-jerking control, and vehicle modelling and parameter estimation. With only a few exceptions, the approaches

This ambitious study documents the underlying features which link the civilizations of the Mediterranean - Phoenician, Greek, Etruscan and Roman - and the Iron Age cultures of central Europe, traditionally associated with the Celts. It deals with the social, economic and cultural interaction in the first millennium BC which culminated in the Roman Empire. The book has three principle themes: the spread of iron-working from its origins in Anatolia to its adoption over most of Europe; the development of a trading system throughout the Mediterrean world after the collapse of Mycenaean Greece and its spread into temperate Europe; and the rise of ever more complex societies, including states and cities, and eventually empires. Dr Collis takes a new look at such key concepts as population movement, diffusion, trade, social structure and spatial organization, with some challenging new views on the Celts in particular.

Automotive Scan Tool PID Diagnostics (Diagnostics Strategies of Modern Automotive Systems) By Mandy Concepcion In this section, the different techniques of scan tool parameter (PID) analysis will be exposed. Techniques involving PID analysis are quickly catching on, due to their speed and accuracy. By properly analyzing the different scanner PIDs, the technician can arrive at the source of the problem much faster and accurately. These procedures give rise to the new term "driver seat diagnostics", since most of the preliminary diagnostic work is done through the scanner. However, these techniques will in no way replace the final manual tests that are a part of every diagnostic path. They are simply geared to point the technician in the right direction. Table of Contents INTRODUCTION (Introduction to scan tool diagnostics and the relevance of using PIDs or scanner parameter to perform the first leg of all diagnostics.) - Theory of Operation Behind the Different PIDs (Describes CARB, the difference between generic and enhanced PIDs, the FTP) - OBD II Generic PIDs (PID calculated and actual values, calculated data relationships, base injection timing, ECM value substitution) - OBD I & II General PID analysis (erasing code-or not, recording, analyzing and pinpoint tests, separating PIDs into groups) - Fuel Delivery Fault Detection (fuel delivery issues, intake air temp. sensor, BARO sensor, Engine LOAD, RPM PID, Short-Term Fuel Trims, Long-Term Fuel Trims, 60% of check engine light issues, block learn/integrators, Example 1: injector fault, Example 2: intake gasket issues, fuel status, ignition timing, MAP/MAF, TPS, O2 sensor, IAC, Closed Throttle, injector pulse width, voltage power, injector dutycycle, fuel trim cell) - Test #1 (Determining an engine's fuel Consumption (rich-lean operation, duty-cycle to fuel trim relationship, O2 sensor to fuel trim relation, FT and vacuum leaks, ignition timing and idle control, test conclusion) - Test # 2 (Misfire Detection Strategy, EGR, Ignition and Mechanical misfires) (misfires and OBD2, scanner misfire detection – a time saver, OBD2 40 and 80 cycle misfire, ignition, injector and EGR density misfire, coil-on-plug, misfires and O2 sensor, lean O2 & Secondary misfire, O2 sensor & injector misfires, leaky injector, EGR and the MAP, Type A, B, C misfires, test conclusion) - Test # 3 (Air/Fuel Ratio Faults) (air-fuel imbalance, MAF and post O2 sensors, open-closed-loop, fuel enable, HC & CO relation to AF issues, test conclusion) - Test # 4 (BARO, MAP & MAF PID analysis) (MAP & valve timing faults, ECM behavior, fuel delivery or duty cycle test, volumetric efficiency, , test conclusion) - Test # 5 (Clogged exhaust) (clogged catalytic converter detection, TPS, MAF and converters, idle and WOT or wide open throttle values, vacuum readings, MAP to WOT chats analysis, engine and MAP vacuum, test conclusion) - Test # 6 (EGR Fault Detection) (EGR and MAP values, ECM reaction to EGR issues, EGR temp sensor, DPFE sensor, EGR and O2-MAP and lift position sensor, EGR and engine pre-loading, EGR and the ECM erroneous high LOAD issues, test conclusion) - Test # 7 (O2 Sensor Heater) (O2 heaters and why?, tough to check O2 heater issues, O2 heater effect on signal output, O2 heater bias voltage, engine off and O2 changing value, test conclusion) - Test # 8 (Resetting Fuel Trims) (resetting injection pulse corrections, long-term and short-term fuel trims, learn condition, Lambda, case study on fuel trims, FT resetting according to manufacturer, test conclusion) - Test # 9 (Engine Cranking Vacuum Test) (MAP/MAF cranking vacuum, vacuum to PID analysis, vacuum leaks, gauge-PID test, sources of leaks, cranking values, test conclusion)

In recent years the amount of software within automobiles has increased up to 100 Million LOC in modern day premium vehicles. Virtually all innovations in automotive engineering in the last decade include software components. Parallel to this increasing amount, testing becomes more vital. Automotive software development follows restrictive guidelines in terms of coding standard, language limitations and processes. Traditionally testing is a core part of automotive development, but the raising number of features increases the time and money required to perform all tests. Repeating them multiple times due to programming errors might jeopardises a cars introduction on the market. SFP is a new approach to forecast bugs already at time of commit, thus to guide test engineers upon defining testing hotspots. This work reports on the first successful application using model driven and code generated automotive software as a case study and a success prediction rate up to 97% upon a bug or fault free commit. A compiled and published dataset is presented along with analysis upon the used software metrics.

Performance data achieved using different machine learning algorithms is given. An indepth analysis upon factors preventing CPFP is conducted. Further usage and practical application areas will conclude the work.

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