Designing Control Loops For Linear And Switching Power Supplies A Tutorial Guide

This book discusses analysis and design techniques for linear feedback control systems using MATLAB® software. By reducing the mathematics, increasing MATLAB working examples, and inserting short scripts and plots within the text, the authors have created a resource suitable for almost any type of user. The book begins with a summary of the properties of linear systems and addresses modeling and model reduction issues. In the subsequent chapters on analysis, the authors introduce time domain, complex plane, and frequency domain techniques. Their coverage of design includes discussions on model-based controller designs, PID controllers, and robust control designs. A unique aspect of the book is its inclusion of a chapter on fractional-order controllers, which are useful in control engineering practice.

The operational amplifier ("op amp") is the most versatile and widely used type of analog IC, used in audio and voltage amplifiers, signal conditioners, signal converters, oscillators, and analog computing systems. Almost every electronic device uses at least one op amp. This book is Texas Instruments' complete professional-level tutorial and reference to operational amplifier theory and applications. Among the topics covered are basic op amp physics (including reviews of current and voltage division, Thevenin's theorem, and transistor models), idealized op amp operation and configuration, feedback theory and methods, single and dual supply operation, understanding op amp parameters, minimizing noise in op amp circuits, and practical applications such as instrumentation amplifiers, signal conditioning, oscillators, active filters, load and level conversions, and analog computing. There is also extensive coverage of circuit construction techniques, including circuit board design, grounding, input and output isolation, using decoupling capacitors, and frequency characteristics of passive components. The material in this book is applicable to all op amp ICs from all manufacturers, not just TI. Unlike textbook treatments of op amp theory that tend to focus on idealized op amp models and configuration, this title uses idealized models only when necessary to explain op amp theory. The bulk of this book is on real-world op amps and their applications; considerations such as thermal effects, circuit noise, circuit buffering, selection of appropriate op amps for a given application, and unexpected effects in passive components are all discussed in detail. *Published in conjunction with Texas Instruments *A single volume, professional-level guide to op amp theory and applications *Covers circuit board layout techniques for manufacturing op amp circuits.

Observers are digital algorithms that combine sensor outputs with knowledge of the system to provide results superior to traditional structures, which rely wholly on sensors. Observers have been used in selected industries for years, but most books explain them with complex mathematics. Observers in Control Systems uses intuitive discussion, software experiments, and supporting analysis to explain the advantages and disadvantages of observers. If you are working in controls and want to improve your control systems, observers could be the technology you need and this book will give you a clear, thorough explanation of how they work and how to use them. Control systems and devices have become the most essential part of nearly all mechanical systems, machines, devices and manufacturing systems throughout the world. Increasingly the efficiency of production, the reliability of output and increased energy savings are a direct result of the quality and deployment of the control system. A modern and essential tool within the engineer's kit is the Observer which helps improve the performance and reduce the cost of these systems. George Ellis is the author of the highly successful Control System Design Guide (Second Edition). Unlike most controls books, which are written by control theorists and academics, Ellis is a leading engineer, designer, author and lecturer working in industry directly with the users of industrial motion control systems. Observers in Control Systems is written for all professional engineers and is designed to be utilized without an in-depth background in control theory. This is a "real-world" book which will demonstrate how observers work and how they can improve your control system. It also shows how observers operate when conditions are not ideal and teaches the reader how to quickly tune an observer in a working system. Software Available online: A free updated and enhanced version of the author's popular Visual ModelQ allows the reader to practice the concepts with Visual ModelQ models on a PC. Based on a virtual laboratory, all key topics are demonstrated with more than twenty control system models. The models are written in Visual ModelQ ,and are available on the Internet to every reader with a PC. Teaches observers and Kalman filters from an intuitive perspective Explains how to reduce control system susceptibility to noise Shows how to design an adaptive controller based on estimating parameter variation using observers Shows how to improve a control system's ability to reject disturbances Key topics are demonstrated with PC-based models of control systems. The models are written in both MatLab® and ModelQ; models are available free of charge

This book is aimed at engineers and technicians who need to have a clear, practical understanding of the essentials of process control, loop tuning and how to optimize the operation of their particular plant or process. The reader would typically be involved in the design, implementation and upgrading of industrial control systems. Mathematical theory has been kept to a minimum with the emphasis throughout on practical applications and useful information. This book will enable the reader to: * Specify and design the loop requirements for a plant using PID control * Identify and apply the essential building blocks in automatic control * Apply the procedures for open and closed loop tuning * Tune control loops with significant dead-times * Demonstrate a clear understanding of analog process control and how to tune analog loops * Explain concepts used by major manufacturers who use the most up-to-date technology in the process control field · A practical focus on the optimization of process and plant · Readers develop professional competencies, not just theoretical knowledge · Reduce dead-time with loop tuning techniques

In this in-depth book, the authors address the concepts and terminology that are needed to work in the field of process control. The material is presented in a straightforward manner that is independent of the control system manufacturer. It is assumed that the reader may not have worked in a process plant environment and may be unfamiliar with the

field devices and control systems. Much of the material on the practical aspects of control design and process applications is based on the authors personal experience gained in working with process control systems. Thus, the book is written to act as a guide for engineers, managers, technicians, and others that are new to process control or experienced control engineers who are unfamiliar with multi-loop control techniques. After the traditional single-loop and multi-loop techniques that are most often used in industry are covered, a brief introduction to advanced control techniques is provided. Whether the reader of this book is working as a process control engineer, working in a control group or working in an instrument department, the information will set the solid foundation needed to understand and work with existing control systems or to design new control applications. At various points in the chapters on process characterization and control design, the reader has an opportunity to apply what was learned using web-based workshops. The only items required to access these workshops are a high-speed Internet connection and a web browser. Dynamic process simulations are built into the workshops to give the reader a realistic "hands-on" experience. Also, one chapter of the book is dedicated to techniques that may be used to create process simulations using tools that are commonly available within most distributed control systems. At various points in the chapters on process characterization and control design, the reader has an opportunity to apply what was learned using web-based workshops. The only items required to access these workshops are a high-speed Internet connection and a web browser. Dynamic process simulations are built into the workshops to give the reader a realistic "hands-on" experience. Also, one chapter of the book is dedicated to techniques that may be used to create process simulations using tools that are commonly available within most distributed control systems. As control techniques are introduced, simple process examples are used to illustrate how these techniques are applied in industry. The last chapter of the book, on process applications, contains several more complex examples from industry that illustrate how basic control techniques may be combined to meet a variety of application requirements. As control techniques are introduced, simple process examples are used to illustrate how these techniques are applied in industry. The last chapter of the book, on process applications, contains several more complex examples from industry that illustrate how basic control techniques may be combined to meet a variety of application requirements.

The vast majority of control systems built today are embedded; that is, they rely on built-in, special-purpose digital computers to close their feedback loops. Embedded systems are common in aircraft, factories, chemical processing plants, and even in cars–a single high-end automobile may contain over eighty different computers. The design of embedded controllers and of the intricate, automated communication networks that support them raises many new questions—practical, as well as theoretical—about network protocols, compatibility of operating systems, and ways to maximize the effectiveness of the embedded hardware. This handbook, the first of its kind, provides engineers, computer scientists, mathematicians, and students a broad, comprehensive source of information and technology to address many questions and aspects of embedded and networked control. Separated into six main sections—Fundamentals, Hardware, Software, Theory, Networking, and Applications—this work unifies into a single reference many scattered articles, websites, and specification sheets. Also included are case studies, experiments, and examples that give a multifaceted view of the subject, encompassing computation and communication considerations.

Over the past decade, tremendous development of wireless communications has changed human life and engineering. Considerable advancement has been made in design and architecture of related RF and microwave circuits. Introduction to Wireless Communication Circuits focuses on special circuits dedicated to the RF level of wireless communications. From oscillators to modulation and demodulation, and from mixers to RF and power amplifier circuits, all are presented in a sequential manner. A wealth of analytical relations is provided in the text alongside various worked out examples. Related problem sets are given at the end of each chapter. Basic concepts of RF Analog Circuit Design are developed in the book. Technical topics discussed include: - Wireless Communication System - RF Oscillators and Phase Locked Loops - Modulator and Demodulator Circuits - RF Mixers - Automatic Gain Control and Limiters - Microwave Circuits, Transmission Lines and S-Parameters - Matching Networks - Linear Amplifier Design and Power Amplifiers - Linearization Techniques This textbook is intended for advanced undergraduate and graduate students, as well as RF Engineers and professionals.

How can you take advantage of feedback control for enterprise programming? With this book, author Philipp K. Janert demonstrates how the same principles that govern cruise control in your car also apply to data center management and other enterprise systems. Through case studies and hands-on simulations, you'll learn methods to solve several control issues, including mechanisms to spin up more servers automatically when web traffic spikes. Feedback is ideal for controlling large, complex systems, but its use in software engineering raises unique issues. This book provides basic theory and lots of practical advice for programmers with no previous background in feedback control. Learn feedback concepts and controller design Get practical techniques for implementing and tuning controllers Use feedback "design patterns" for common control scenarios Maintain a cache's "hit rate" by automatically adjusting its size Respond to web traffic by scaling server instances automatically Explore ways to use feedback principles with queueing systems Learn how to control memory consumption in a game engine Take a deep dive into feedback control theory

This text introduces the fundamental techniques for controlling dead-time processes from simple monovariable to complex multivariable cases. Dead-time-process-control problems are studied using classical proportional-integral-differential (PID) control for the simpler examples and dead-time-compensator (DTC) and model predictive control (MPC) methods for progressively more complex ones. Downloadable MATLAB® code makes the examples and ideas more convenient and simpler.

Nonlinear Process Control assembles the latest theoretical and practical research on design, analysis and application of nonlinear process control strategies. It presents detailed coverage of all three major

elements of nonlinear process control: identification, controller design, and state estimation. Nonlinear Process Control reflects the contributions of eleven leading researchers in the field. It is an ideal textbook for graduate courses in process control, as well as a concise, up-to-date reference for control engineers.

An excellent introduction to feedback control system design, this book offers a theoretical approach that captures the essential issues and can be applied to a wide range of practical problems. Its explorations of recent developments in the field emphasize the relationship of new procedures to classical control theory, with a focus on single input and output systems that keeps concepts accessible to students with limited backgrounds. The text is geared toward a single-semester senior course or a graduate-level class for students of electrical engineering. The opening chapters constitute a basic treatment of feedback design. Topics include a detailed formulation of the control design program, the fundamental issue of performance/stability robustness tradeoff, and the graphical design technique of loopshaping. Subsequent chapters extend the discussion of the loopshaping technique and connect it with notions of optimality. Concluding chapters examine controller design via optimization, offering a mathematical approach that is useful for multivariable systems.

Advanced Control Design with Application to Electromechanical Systems represents the continuing effort in the pursuit of analytic theory and rigorous design for robust control methods. The book provides an overview of the feedback control systems and their associated definitions, with discussions on finite dimension vector spaces, mappings and convex analysis. In addition, a comprehensive treatment of continuous control system design is presented, along with an introduction to control design topics pertaining to discrete-time systems. Other sections introduces linear H1 and H2 theory, dissipativity analysis and synthesis, and a wide spectrum of models pertaining to electromechanical systems. Finally, the book examines the theory and mathematical analysis of multiagent systems. Researchers on robust control theory and electromechanical systems and graduate students working on robust control will benefit greatly from this book. Introduces a coherent and unified framework for studying robust control theory Provides the control-theoretic background required to read and contribute to the research literature Presents the main ideas and demonstrations of the major results of robust control theory Includes MATLAB codes to implement during research

Advanced Control Engineering provides a complete course in control engineering for undergraduates of all technical disciplines. Included are real-life case studies, numerous problems, and accompanying MatLab programs.

Harness Powerful SPICE Simulation and Design Tools to Develop Cutting-Edge Switch-Mode Power Supplies Switch-Mode Power Supplies: SPICE Simulations and Practical Designs is a comprehensive resource on using SPICE as a power conversion design companion. This book uniquely bridges analysis and market reality to teach the development and marketing of state-of-the art switching converters. Invaluable to both the graduating student and the experienced design engineer, this guide explains how to derive founding equations of the most popular converters...design safe, reliable converters through numerous practical examples...and utilize SPICE simulations to virtually breadboard a converter on the PC before using the soldering iron. Filled with more than 600 illustrations, Switch-Mode Power Supplies: SPICE Simulations and Practical Designs enables you to: Derive founding equations of popular converters Understand and implement loop control via the book-exclusive small-signal models Design safe, reliable converters through practical examples Use SPICE simulations to virtually breadboard a converter on the PC Access design spreadsheets and simulation templates on the accompanying CD-ROM, with numerous examples running on OrCADË, ICAPSË, ?CapË, TINAË, and more Inside This Powerful SPICE Simulation and Design Resource • Introduction to Power Conversion • Small-Signal Modeling • Feedback and Control Loops • Basic Blocks and Generic Models • Simulation and Design of Nonisolated Converters • Simulation and Design of Isolated Converters-Front-End Rectification and Power Factor Correction • Simulation and Design of Isolated Converters-The Flyback • Simulation and Design of Isolated Converters-The Forward

This textbook provides a unique introduction to Feedback Control. It differs from typical control books by presenting principles in the context of three specific design examples: a one link robot arm, a pendulum on a cart, and a satellite attitude problem. These three design examples illustrate the full process of implementing control strategies on mechanical systems. The book begins by introducing the Euler Lagrange method for modeling mechanical systems and discusses computer simulation of these models. Linear design models are developed, specifically transfer function and state space models, that capture the behavior of the system around equilibria. The book then presents three different design strategies for output feedback control: PID control, observer based design, and loopshaping design methods based on the frequency response of the system. Extensive examples show how the controllers are implemented in Simulink, Matlab object oriented code, and Python.

Linear Circuit Transfer Functions: An introduction to Fast Analytical Techniques teaches readers how to determine transfer functions of linear passive and active circuits by applying Fast Analytical Circuits Techniques. Building on their existing knowledge of classical loop/nodal analysis, the book improves and expands their skills to unveil transfer functions in a swift and efficient manner. Starting with simple examples, the author explains step-by-step how expressing circuits time constants in different configurations leads to writing transfer functions in a compact and insightful way. By learning how to organize numerators and denominators in the fastest possible way, readers will speed-up analysis and predict the frequency response of simple to complex circuits. In some cases, they will be able to derive the final expression by inspection, without writing a line of algebra. Key features: Emphasizes analysis through employing time constant-based methods discussed in other text books but not widely used or explained. Develops current techniques on transfer functions, to fast analytical techniques leading to low-entropy transfer functions immediately exploitable for analysis purposes. Covers calculation techniques pertinent to different fields, electrical, electronics, signal processing etc. Describes how a technique is applied and demonstrates this through real design examples. All Mathcad® files used in examples and problems are freely available for download. An ideal reference for electronics or electrical engineering professionals as well as BSEE and MSEE students, this book will help teach them how to: become skilled in the art of determining transfer function by using less algebra and obtaining results in a more effectual way; gain insight into a circuit's operation by understanding how time constants rule dynamic responses; apply Fast Analytical Techniques to simple and complicated circuits, passive or active and be more efficient at solving problems.

Designing Control Loops for Linear and Switching Power SuppliesA Tutorial GuideArtech House

Loop control is an essential area of electronics engineering that today's professionals need to master. Rather than delving into extensive theory, this practical book focuses on what you really need to know for compensating or stabilizing a given control system. You can turn instantly to practical sections with numerous design examples and ready-made formulas to help you with your projects in the field. You also find coverage of the underpinnings and principles of control loops so you can gain a more complete understanding of the material. This authoritative volume explains how to conduct analysis of control systems and provides extensive details on practical compensators. It helps you measure your system, showing how to verify if a prototype is stable and features enough design margin. Moreover, you learn how to secure high-volume production by bench-verified safety margins.

An instructive reference that will help control researchers and engineers, interested in a variety of industrial processes, to take advantage of a powerful tuning method for the ever-popular PID control paradigm. This monograph presents explicit PID tuning rules for linear control loops regardless of process complexity. It shows the reader how such loops achieve zero steady-position,

velocity, and acceleration errors and are thus able to track fast reference signals. The theoretical development takes place in the frequency domain by introducing a general-transfer-function-known process model and by exploiting the principle of the magnitude optimum criterion. It is paralleled by the presentation of real industrial control loops used in electric motor drives. The application of the proposed tuning rules to a large class of processes shows that irrespective of the complexity of the controlled process the shape of the step and frequency response of the control loop exhibits a specific performance. This specific performance, along with the PID explicit solution, formulates the basis for developing an automatic tuning method for the PID controller parameters which is a problem often met in many industry applications—temperature, pH, and humidity control, ratio control in product blending, and boiler-drum level control, for example. The process of the model is considered unknown and controller parameters are tuned automatically such that the aforementioned performance is achieved. The potential both for the explicit tuning rules and the automatic tuning method is demonstrated using several examples for benchmark process models recurring frequently in many industry applications.

Numerous examples highlight this treatment of the use of linear quadratic Gaussian methods for control system design. It explores linear optimal control theory from an engineering viewpoint, with illustrations of practical applications. Key topics include loop-recovery techniques, frequency shaping, and controller reduction. Numerous examples and complete solutions. 1990 edition. The book blends readability and accessibility common to undergraduate control systems texts with the mathematical rigor necessary to form a solid theoretical foundation. Appendices cover linear algebra and provide a Matlab overiview and files. The reviewers pointed out that this is an ambitious project but one that will pay off because of the lack of good up-to-date textbooks in the area.

Control Systems Design Guide has helped thousands of engineers to improve machine performance. This fourth edition of the practical guide has been updated with cutting-edge control design scenarios, models and simulations enabling apps from battlebots to solar collectors. This useful reference enhances coverage of practical applications via the inclusion of new control system models, troubleshooting tips, and expanded coverage of complex systems requirements, such as increased speed, precision and remote capabilities, bridging the gap between the complex, math-heavy control theory taught in formal courses, and the efficient implementation required in real industry settings. George Ellis is Director of Technology Planning and Chief Engineer of Servo Systems at Kollmorgen Corporation, a leading provider of motion systems and components for original equipment manufacturers (OEMs) around the globe. He has designed an applied motion control systems professionally for over 30 years He has written two well-respected books with Academic Press, Observers in Control Systems and Control System Design Guide, now in its fourth edition. He has contributed articles on the application of controls to numerous magazines, including Machine Design, Control Engineering, Motion Systems Design, Power Control and Intelligent Motion, and Electronic Design News. Explains how to model machines and processes, including how to measure working equipment, with an intuitive approach that avoids complex math Includes coverage on the interface between control systems and digital processors, reflecting the reality that most motion systems are now designed with PC software Of particular interest to the practicing engineer is the addition of new material on real-time, remote and networked control systems Teaches how control systems work at an intuitive level, including how to measure, model, and diagnose problems, all without the unnecessary math so common in this field Principles are taught in plain language and then demonstrated with dozens of software models so the reader fully comprehend the material (The models and software to replicate all material in the book is provided without charge by the author at www.QxDesign.com) New material includes practical uses of Rapid Control Prototypes (RCP) including extensive examples using National Instruments LabVIEW

THE LATEST SPICE SIMULATION AND DESIGN TOOLS FOR CREATING STATE-OF-THE-ART SWITCHMODE POWER SUPPLIES Fully updated to incorporate new SPICE features and capabilities, this practical guide explains, step by step, how to simulate, test, and improve switch-mode power supply designs. Detailed formulas with founding equations are included. Based on the author's continued research and in-depth, handson work in the field, this revised resource offers a collection of the latest SPICE solutions to the most difficult problem facing power supply designers: creating smaller, more heat-efficient power supplies in shorter design cycles. NEW to this edition: Complete analysis of rms currents for the three basic cells in CCM and DCM PWM switch at work in the small-signal analysis of the DCM boost and the QR flyback OTA-based compensators Complete transistor-level TL431 model Small-signal analysis of the borderline-operated boost PFC circuit operated in voltage or current mode All-over power phenomena in QR or fixed-frequency discontinuous/continuous flyback converters Small-signal model of a QR flyback converter Small-signal model of the active clamp forward converter operated in voltagemode control Electronic content—design templates and examples available online Switch-Mode Power Supplies: SPICE Simulations and Practical Designs, Second Edition, covers: Small-signal modeling * Feedback and ciontrol loops * Basic blocks and generic switched models * Nonisolated converters * Off-line converters * Flyback converters * Forward converters * Power factor correction

Ready-made SPICE power supply solutions Now you can get solutions to the most difficult problems facing power supply designers: shrinking size and increased thermal constraints. Christophe Basso's SMPS SPICE Cookbook is a complete designer's toolkit with tested, ready-to-run SPICE models on an accompanying CD-ROM. The models come in all three SPICE flavors with demo versions. You can start from scratch, installing the software and simulating the examples in the book without any SPICE experience whatsoever. All the common SMPS topologies are covered: buck, boost, buck-boost, and SEPIC. Each is described in terms of relative strengths and weaknesses and then modeled. Just turn to the CD, pull out the model in the flavor of SPICE you use, plug in your own values – and out comes a design solution. All the models in the book have been carefully simulated and tested. A special website even lets you access new models that will be posted on a continuing basis

For both undergraduate and graduate courses in Control System Design. Using a "how to do it" approach with a strong emphasis on real-world design, this text provides comprehensive, single-source coverage of the full spectrum of control system design. Each of the text's 8 parts covers an area in control--ranging from signals and systems (Bode Diagrams, Root Locus, etc.), to SISO control (including PID and Fundamental Design Trade-Offs) and MIMO systems (including Constraints, MPC, Decoupling, etc.). Digital controllers are part of nearly all modern personal, industrial, and transportation systems. Every senior or graduate student of electrical, chemical or mechanical engineering should therefore be familiar with the basic theory of digital controllers. This new text covers the fundamental principles and applications of digital control engineering, with emphasis on engineering design. Fadali and Visioli cover analysis and design of digitally controlled systems and describe applications of digital controls in a wide range of

fields. With worked examples and Matlab applications in every chapter and many end-of-chapter assignments, this text provides both theory and practice for those coming to digital control engineering for the first time, whether as a student or practicing engineer. Extensive Use of computational tools: Matlab sections at end of each chapter show how to implement concepts from the chapter Frees the student from the drudgery of mundane calculations and allows him to consider more subtle aspects of control system analysis and design An engineering approach to digital controls: emphasis throughout the book is on design of control systems. Mathematics is used to help explain concepts, but throughout the text discussion is tied to design and implementation. For example coverage of analog controls in chapter 5 is not simply a review, but is used to show how analog control systems map to digital control systems Review of Background Material: contains review material to aid understanding of digital control analysis and design. Examples include discussion of discrete-time systems in time domain and frequency domain (reviewed from linear systems course) and root locus design in s-domain and z-domain (reviewed from feedback control course) Inclusion of Advanced Topics In addition to the basic topics required for a one semester senior/graduate class, the text includes some advanced material to make it suitable for an introductory graduate level class or for two quarters at the senior/graduate level. Examples of optional topics are state-space methods, which may receive brief coverage in a one semester course, and nonlinear discrete-time systems Minimal Mathematics Prerequisites The mathematics background required for understanding most of the book is based on what can be reasonably expected from the average electrical, chemical or mechanical engineering senior. This background includes three semesters of calculus, differential equations and basic linear algebra. Some texts on digital control require more

In recent decades, a comprehensive new framework for the theory and design of control systems has emerged. It treats a range of significant and ubiquitous design problems more effectively than the conventional framework. Control Systems Design brings together contributions from the originators of the new framework in which they explain, expand and revise their research work. It is divided into four parts: - basic principles, including those of matching and inequalities with adjustments for robust matching and matching based on H-infinity methods and linear matrix inequalities; - computational methods, including matching conditions for transient inputs and design of a sampled-data control system; - search methods including search with simulated annealing, genetic algorithms and evaluation of the node array method; - case studies, including applications in distillation, benchmarking critical control of magnetic levitation systems and the use of the principle of matching in cruise control.

This open access Brief introduces the basic principles of control theory in a concise self-study guide. It complements the classic texts by emphasizing the simple conceptual unity of the subject. A novice can quickly see how and why the different parts fit together. The concepts build slowly and naturally one after another, until the reader soon has a view of the whole. Each concept is illustrated by detailed examples and graphics. The full software code for each example is available, providing the basis for experimenting with various assumptions, learning how to write programs for control analysis, and setting the stage for future research projects. The topics focus on robustness, design trade-offs, and optimality. Most of the book develops classical linear theory. The last part of the book considers robustness with respect to nonlinearity and explicitly nonlinear extensions, as well as advanced topics such as adaptive control and model predictive control. New students, as well as scientists from other backgrounds who want a concise and easy-to-grasp coverage of control theory, will benefit from the emphasis on concepts and broad understanding of the various approaches.

The only method of circuit analysis known to most engineers and students is nodal or loop analysis. Although this works well for obtaining numerical solutions, it is almost useless for obtaining analytical solutions in all but the simplest cases. In this unusual 2002 book, Vorpérian describes remarkable alternative techniques to solve, almost by inspection, complicated linear circuits in symbolic form and obtain meaningful analytical answers for any transfer function or impedance. Although not intended to replace traditional computer-based methods, these techniques provide engineers with a powerful set of tools for tackling circuit design problems. They also have great value in enhancing students' understanding of circuit operation, making this an ideal course book, and numerous problems and worked examples are included. Originally developed by Professor David Middlebrook and others at Caltech (California Institute of Technology), the techniques described here are now widely taught at institutions and companies around the world.

The definitive guide to switchmode power supply design--fully updated Covering the latest developments and techniques, Switchmode Power Supply Handbook, third edition is a thorough revision of the industry-leading resource for power supply designers. New design methods required for powering small, high-performance electronic devices are presented. Based on the authors' decades of experience, the book is filled with real-world solutions and many nomograms, and features simplified theory and mathematical analysis. This comprehensive volume explains common requirements for direct operation from the AC line supply and discusses design, theory, and practice. Engineering requirements of switchmode systems and recommendations for active power factor correction are included. This practical guide provides you with a working knowledge of the latest topologies along with step-by-step approaches to component decisions to achieve reliable and cost-effective power supply designs. Switchmode Power Supply Handbook, third edition covers: Functional requirements of direct off-line switchmode power supplies Power components selection and transformer designs for converter circuits Transformer, choke, and thermal design Input filters, RFI control, snubber circuits, and auxiliary systems Active power factor correction system design Worked examples of would components Examples of fully resonant and quasi-resonant systems A resonant inverter fluorescent ballast An example of high-power phase shift modulated system A new MOSFET resonant inverter drive scheme A single-control, wide-range wave oscillator

Process Control: Modeling, Design, and Simulation is the first complete introduction to process control that fully integrates software tools-helping you master critical techniques hands-on, using MATLAB-based computer simulations. Author B. Wayne Bequette includes process control diagrams, dynamic modeling, feedback control, frequency response

analysis techniques, control loop tuning, and start-to-finish chemical process control case studies.

The latest techniques for designing state-of-the-art power supplies, including resonant (LLC) converters Extensively revised throughout, Switching Power Supply Design & Optimization, Second Edition, explains how to design reliable, high-performance switching power supplies for today's cutting-edge electronics. The book covers modern topologies and converters and features new information on designing or selecting bandgap references, transformer design using detailed new design charts for proximity effects, Buck efficiency loss teardown diagrams, active reset techniques, topology morphology, and a meticulous AC-DC front-end design procedure. This updated resource contains design charts and numerical examples for comprehensive feedback loop design, including TL431, plus the world's first top-down simplified design methodology for wide-input resonant (LLC) converters. A step-by-step comparative design procedure for Forward and Flyback converters is also included in this practical guide. The new edition covers: Voltage references DC-DC converters: topologies to configurations Contemporary converters, composites, and related techniques Discontinuous conduction mode Comprehensive front-end design in AC-DC power conversion Topologies for AC-DC applications Tapped-inductor (autotransformer-based) converters Selecting inductors for DC-DC converters Flyback and Forward converter transformer design Forward and Flyback converters: step-by-step design and comparison PCBs and thermal management Closing the loop: feedback and stability, including TL431 Practical EMI filter design Reset techniques in Flyback and Forward converters Reliability, testing, and safety issues Unraveling and optimizing Buck converter efficiency Introduction to soft-switching and detailed LLC converter design methodology with PSpice simulations Practical circuits, design ideas, and component FAQs

Transfer Functions of Switching Converters teaches readers how to determine transfer functions of switching power supplies commonly encountered in consumer and industrial markets. The book starts with a smooth introduction to switching cells, going into the details of the first steps of linearization and small-signal modulation. You will then learn how the PWM switch model was derived and how to apply it to the basic structures operated in fixed switching frequency and various operating conditions like continuous and discontinuous modes in voltage- or current-mode control. The model is extended to other control schemes like quasi-resonance, constant on- and off-time converters, all with an associated small-signal version. The following chapters explore the founding structures like the buck, the boost and buck-boost cells, later covering their isolated versions like forward or flyback converters. The last chapter deals with more complicated structures like ?uk, Zeta, SEPIC and LLC.

The essential introduction to the principles and applications of feedback systems—now fully revised and expanded This textbook covers the mathematics needed to model, analyze, and design feedback systems. Now more user-friendly than ever, this revised and expanded edition of Feedback Systems is a one-volume resource for students and researchers in mathematics and engineering. It has applications across a range of disciplines that utilize feedback in physical, biological, information, and economic systems. Karl Åström and Richard Murray use techniques from physics, computer science, and operations research to introduce control-oriented modeling. They begin with state space tools for analysis and design, including stability of solutions, Lyapunov functions, reachability, state feedback observability, and estimators. The matrix exponential plays a central role in the analysis of linear control systems, allowing a concise development of many of the key concepts for this class of models. Åström and Murray then develop and explain tools in the frequency domain, including transfer functions, Nyquist analysis, PID control, frequency domain design, and robustness. Features a new chapter on design principles and tools, illustrating the types of problems that can be solved using feedback Includes a new chapter on fundamental limits and new material on the Routh-Hurwitz criterion and root locus plots Provides exercises at the end of every chapter Comes with an electronic solutions manual An ideal textbook for undergraduate and graduate students Indispensable for researchers seeking a self-contained resource on control theory

A contemporary evaluation of switching power design methods with real world applications • Written by a leading author renowned in his field • Focuses on switching power supply design, manufacture and debugging • Switching power supplies have relevance for contemporary applications including mobile phone chargers, laptops and PCs • Based on the authors' successful "Switching Power Optimized Design 2nd Edition" (in Chinese) • Highly illustrated with design examples of real world applications

This book covers the most important issues from classical and robust control, deterministic and stochastic control, system identification, and adaptive and iterative control strategies. It covers most of the known control system methodologies using a new base, the Youla parameterization (YP). This concept is introduced and extended for TDOF control loops. The Keviczky-Banyasz parameterization (KP) method developed for closed loop systems is also presented. The book is valuable for those who want to see through the jungle of available methods by using a unified approach, and for those who want to prepare computer code with a given algorithm. Provides comprehensive coverage of the most widely used control system methodologies The first book to use the Youla parameterization (YP) as a common base for comparison and algorithm development Compares YP and Keviczky-Banyasz (KB) parameterization to help you write your own computer algorithms

This book can serve as a reference resource for those very same design and control engineers who help connect their everyday experience in design with the control field of mechatronics. This book also consists of basic and main mechatronic system's laboratory applications for use in research and development departments in academia, government, and industry, and it can be used as a reference source in university libraries. It can also be used as a resource for scholars interested in understanding and explaining the engineering design and control process and for engineering students studying within the traditional structure of most engineering departments and colleges. It is evident that there is an expansion of mechatronics laboratories and classes in the university environment worldwide.

The World's #1 Guide to Power Supply Design Now Updated! Recognized worldwide as the definitive guide to power supply design for over 25 years, Switching Power Supply Design has been updated to cover the latest innovations in technology, materials, and components. This Third Edition presents the basic principles of the most commonly used topologies, providing you with the essential information required to design cutting-edge power supplies. Using a tutorial, how-and-why approach, this expert resource is filled with design examples, equations, and charts. The Third Edition of Switching Power Supply Design features: Designs for many of the most useful switching power supply topologies The core principles required to solve day-to-day design problems A strong focus on the essential basics of transformer and magnetics design New to this edition: a full chapter on choke design and optimum drive conditions for modern fast IGBTs Get Everything You Need to Design a Complete Switching Power Supply: Fundamental Switching Regulators * Push-Pull and Forward Converter Topologies * Half- and Full-Bridge Converter Topologies * Flyback Converter Topologies * Current-Mode and Current-Fed Topologies * Miscellaneous Topologies * Transformer and Magnetics Design * High-Frequency Choke Design * Optimum Drive Conditions for Bipolar Power Transistors, MOSFETs, Power Transistors, and IGBTs * Drive Circuits for Magnetic Amplifiers * Postregulators * Turn-on, Turn-off Switching Losses and Low Loss Snubbers * Feedback-Loop Stabilization * Resonant Converter Waveforms * Power Factor and Power Factor Correction * High-Frequency Power Sources for Fluorescent Lamps, and Low-Input-Voltage Regulators for Laptop Computers and Portable Equipment

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